

7. MAC 112

7.1. Technical Data

Designation	Symbol	Unit	Motor type MAC ...			
			112 A - - Z ·	112 B - - P ·	112 C - - K ·	112 D - - H ·
Nominal motor speed ¹⁾	n	min ⁻¹	1500	1500	1500	1500
Continuous torque at standstill ²⁾	M _{dN}	Nm	10.7 (13.0) ⁵⁾	18.2 (29) ⁵⁾	28.0 (44.0) ⁵⁾	38.0 (57.0) ⁵⁾
Continuous current at standstill	I _{dN}	A	14.5 (17.2) ⁵⁾	21.0 (33.0) ⁵⁾	31.0 (49.0) ⁵⁾	42.0 (63) ⁵⁾
Rotor moment of inertia ³⁾	J _M	kgm ²	61 x 10 ⁻⁴	120 x 10 ⁻⁴	170 x 10 ⁻⁴	230 x 10 ⁻⁴
Torque constant at 20 °C	K _m	Nm/A	0.820	0.910	1.000	1.010
Windings resistance at 20 °C	R _A	Ohm	0.990	0.450	0.270	0.176
Windings inductance	L _A	mH	10.0	6.3	4.5	3.2
Maximum peak of pulse current	I _{peak}	A	54	97	141	195
Thermal time constant	T _{th}	min	100 (75) ⁵⁾	90 (60) ⁵⁾	100 (75) ⁵⁾	120 (90) ⁵⁾
Mass ⁴⁾	m _M	kg	25	36	48	59
			112 A - - V ·	112 B - - L ·	112 C - - H ·	112 D - - F ·
Nominal motor speed ¹⁾	n	min ⁻¹	2000	2000	2000	2000
Continuous torque at standstill ²⁾	M _{dN}	Nm	10.5 (13.0) ⁵⁾	17.5 (29) ⁵⁾	27.0 (44.0) ⁵⁾	38.0 (57.0) ⁵⁾
Continuous current at standstill	I _{dN}	A	18.5 (22.9) ⁵⁾	26.3 (43.5) ⁵⁾	41.0 (67.0) ⁵⁾	56.0 (83) ⁵⁾
Rotor moment of inertia ³⁾	J _M	kgm ²	61 x 10 ⁻⁴	120 x 10 ⁻⁴	170 x 10 ⁻⁴	230 x 10 ⁻⁴
Torque constant at 20 °C	K _m	Nm/A	0.630	0.740	0.730	0.760
Windings resistance at 20 °C	R _A	Ohm	0.650	0.260	0.150	0.110
Windings inductance	L _A	mH	6.0	3.5	2.5	1.8
Maximum peak of pulse current	I _{peak}	A	71	130	195	260
Thermal time constant	T _{th}	min	100 (75) ⁵⁾	90 (60) ⁵⁾	100 (75) ⁵⁾	120 (90) ⁵⁾
Mass ⁴⁾	m _M	kg	25	36	48	59
			112 A - - L ·	112 B - - G ·	112 C - - E ·	112 D - - E ·
Nominal motor speed ¹⁾	n	min ⁻¹	3000	3000	3000	3000
Continuous torque at standstill ²⁾	M _{dN}	Nm	9.8 (13.0) ⁵⁾	16.0 (29) ⁵⁾	24.0 (44.0) ⁵⁾	35.0 (57.0) ⁵⁾
Continuous current at standstill	I _{dN}	A	31.0 (41.3) ⁵⁾	41.0 (75.0) ⁵⁾	57.0 (104) ⁵⁾	63.0 (102) ⁵⁾
Rotor moment of inertia ³⁾	J _M	kgm ²	61 x 10 ⁻⁴	120 x 10 ⁻⁴	170 x 10 ⁻⁴	230 x 10 ⁻⁴
Torque constant at 20 °C	K _m	Nm/A	0.350	0.430	0.470	0.620
Windings resistance at 20 °C	R _A	Ohm	0.180	0.090	0.060	0.070
Windings inductance	L _A	mH	1.9	1.2	1.0	1.3
Maximum peak of pulse current	I _{peak}	A	130	223	312	312
Thermal time constant	T _{th}	min	100 (75) ⁵⁾	90 (60) ⁵⁾	100 (75) ⁵⁾	120 (90) ⁵⁾
Mass ⁴⁾	m _M	kg	25	36	48	59
			112 C - - C ·			
Nominal motor speed ¹⁾	n	min ⁻¹			5000	
Continuous torque at standstill ²⁾	M _{dN}	Nm			27.0	
Continuous current at standstill	I _{dN}	A			87.5	
Rotor moment of inertia ³⁾	J _M	kgm ²			170 x 10 ⁻⁴	
Torque constant at 20 °C	K _m	Nm/A			0.330	
Windings resistance at 20 °C	R _A	Ohm			0.030	
Windings inductance	L _A	mH			0.5	
Maximum peak of pulse current	I _{peak}	A			400	
Thermal time constant	T _{th}	min			100	
Mass ⁴⁾	m _M	kg			48	

1) The usable motor speed is determined by the drive used.
 Only those usable speeds n_{max} found in the selection lists of the motor-drive combinations are binding.
 2) With 60K overtemperature at the motor housing.
 Continuous torque can be limited by the drive. See selection data.
 3) With tacho-generator, without holding brake
 4) With tacho-generator, without holding brake, without blower.
 5) Parenthetical values apply to versions with surface cooling.

Fig 7.1: Type-dependent motor data

Designation	Symbol	Unit	Data		
Permissible ambient temperature	T _{um}	°C	0 ... +45		
Permissible storage and transport temperature	T _L	°C	-20 ... +80		
Maximum installation elevation		m	1000 m. above sea level		
Protection category			IP 65		
Insulation classification			F		
Housing coat			Black prime coat (RAL9005)		
Voltage constant of the tachogenerator ¹⁾	C _w	Vs/rad V/min ⁻¹	0.0143 1.5/1000	0.0286 3/1000	0.0572 6/1000 ²⁾

1) Tachovoltage can be selected application-related.
 2) If 6 V/1000 min⁻¹ tachometer is used, then usable speed is limited to 1600 min⁻¹.

Fig 7.2: General data MAC 112

Designation	Symbol	Unit	Data holding brake		
Principle of action	M _H	Nm	Standard	heavy-duty ¹⁾ electrically released	extra heavy-duty ¹⁾
Holding torque	U _N	V	14	40	60
Nominal voltage	I _N	A	0.75	1.35	1.35
Nominal current	J _B	kgm ²	3.6 × 10 ⁻⁴	32 × 10 ⁻⁴	32 × 10 ⁻⁴
Moment of inertia	t _L	ms	70	150	150
Release delay	t _K	ms	30	30	30
Clamping delay	m _B	kg	1.1	3.5	3.5

¹⁾ Not available with MAC 112A .

Fig 7.3: Technical data - holding brake

Designation	Symbol	Unit	Axial cooling	Radial cooling
Power consumption	S _N	VA	40/42	40/42
Nominal voltage	U _N	V	AC 230 or 115 ¹⁾	AC 230 or 115 ¹⁾
Frequency	f	Hz	50/60	50/60
Mass	m _L	kg	approx.. 3.3 ²⁾	approx.. 3.2 ²⁾
Protection category blower unit			IP 24	IP 24
Protection category blower motor			IP 44	IP 44

¹⁾ 115 V special design
²⁾ Blower shroud for motor with tacho feedback.

Fig 7.4: Technical data - surface cooling

7.2. Torque-Speed Characteristics

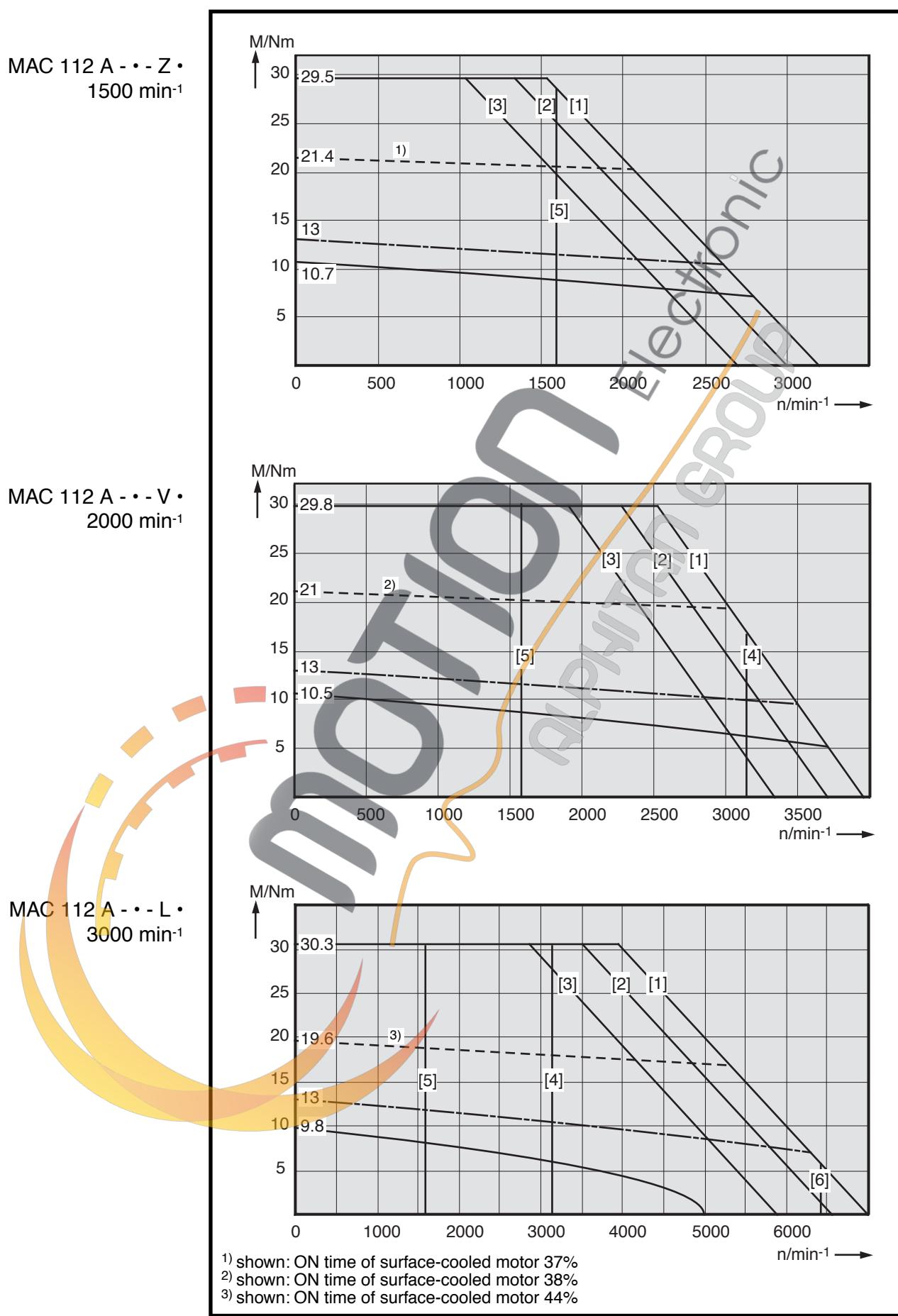


Fig 7.5: Torque-speed characteristics MAC 112

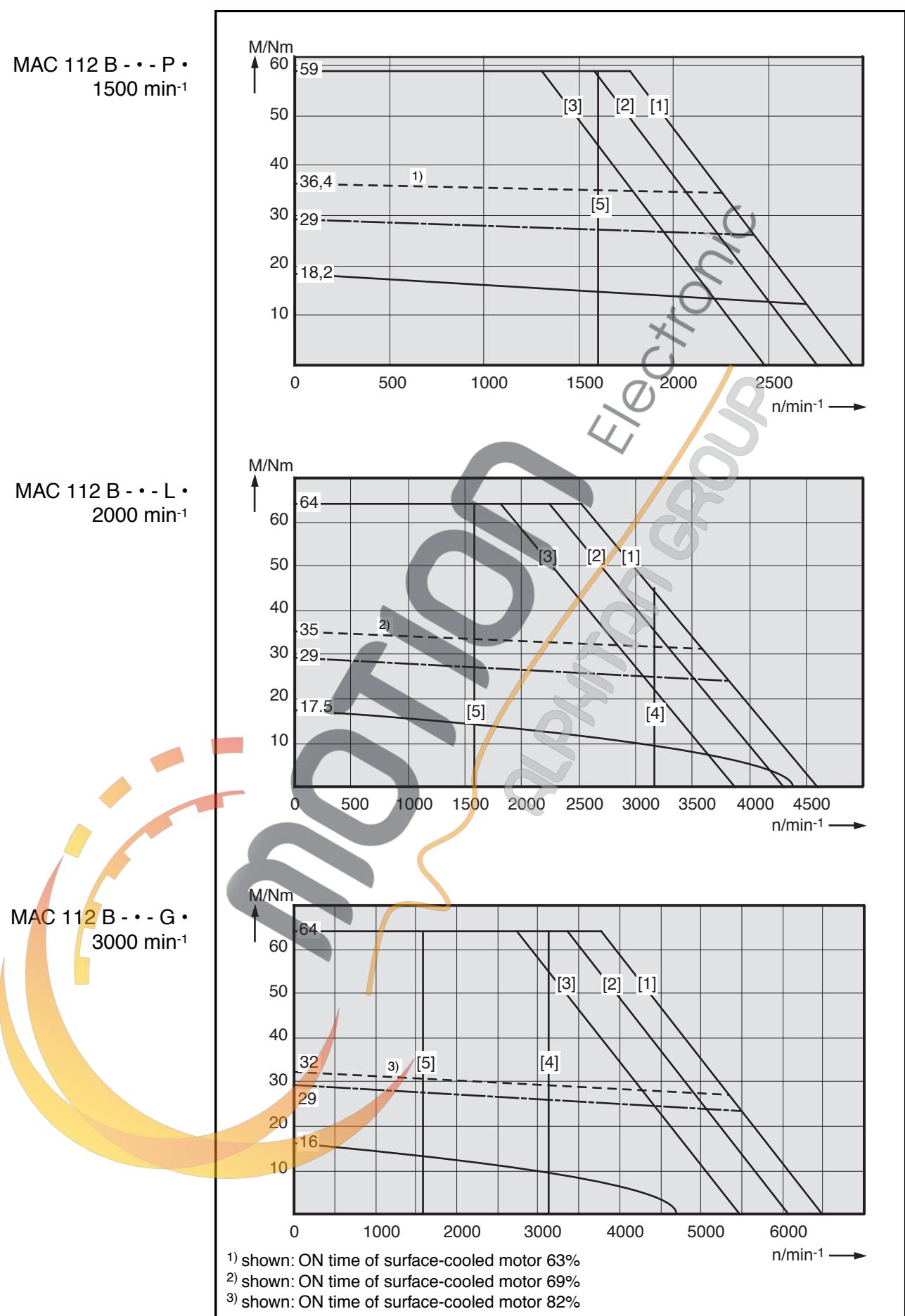


Fig 7.6: Torque-speed characteristics MAC 112

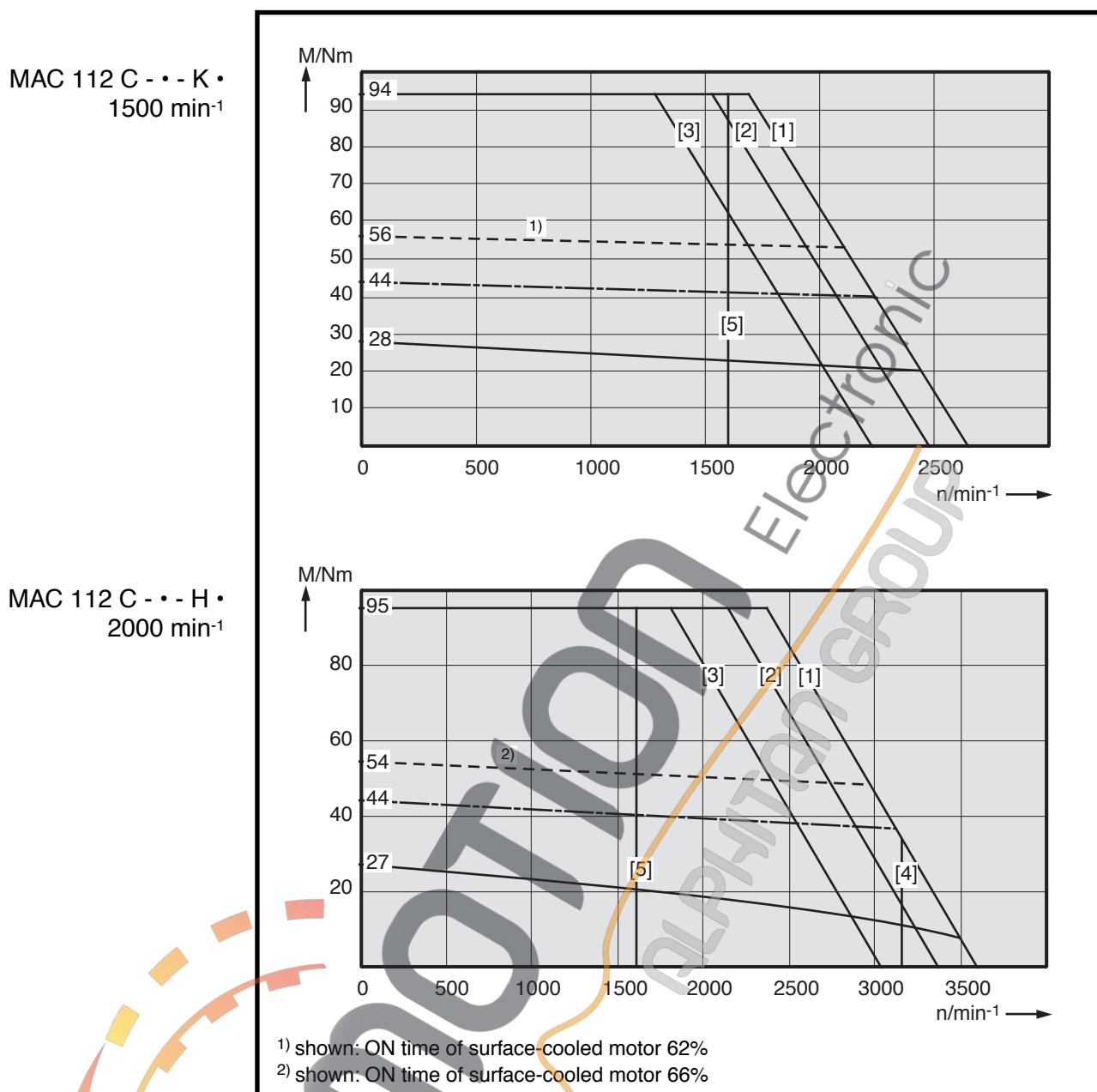
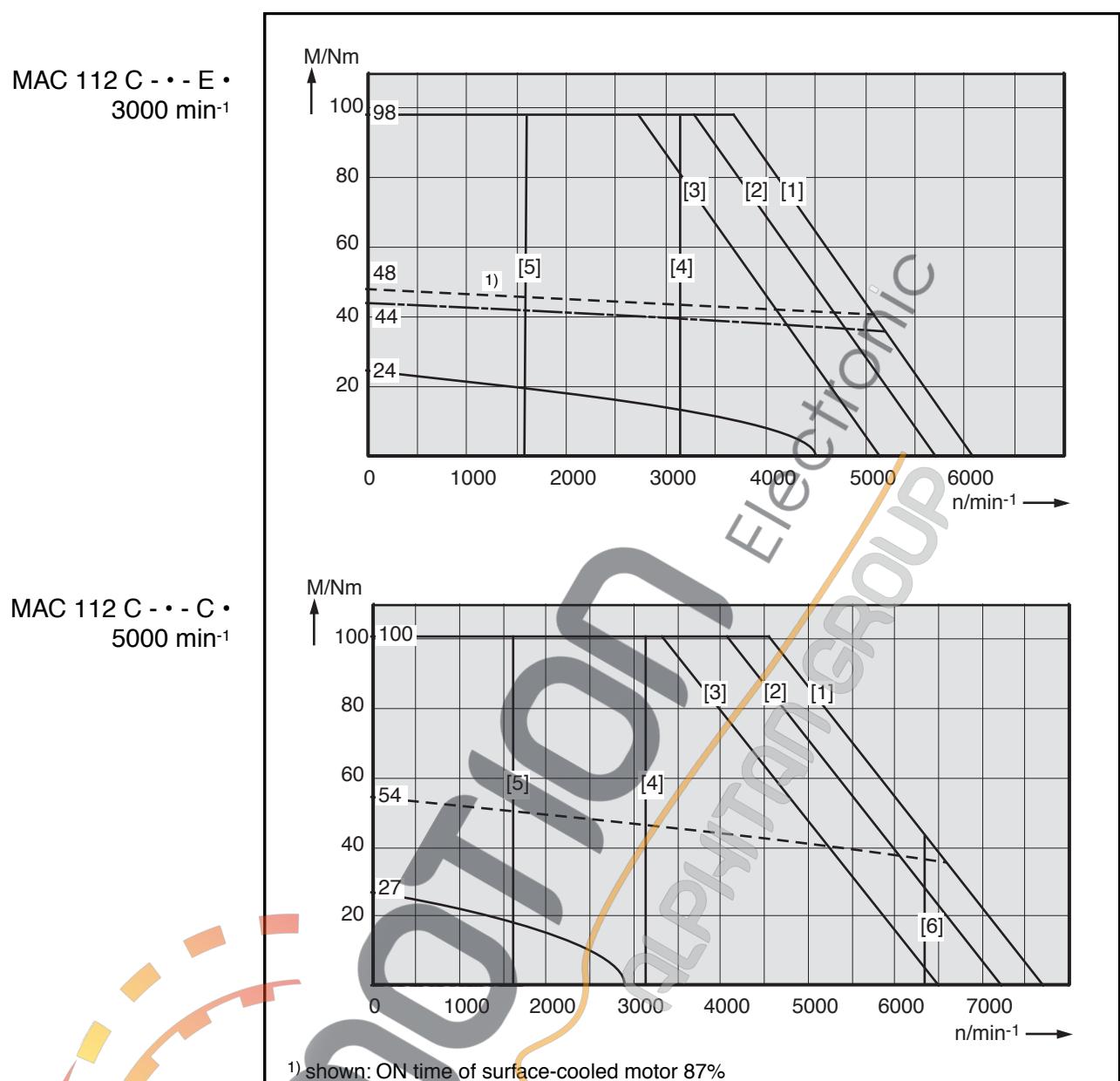


Fig 7.7: Torque-speed characteristics MAC 112



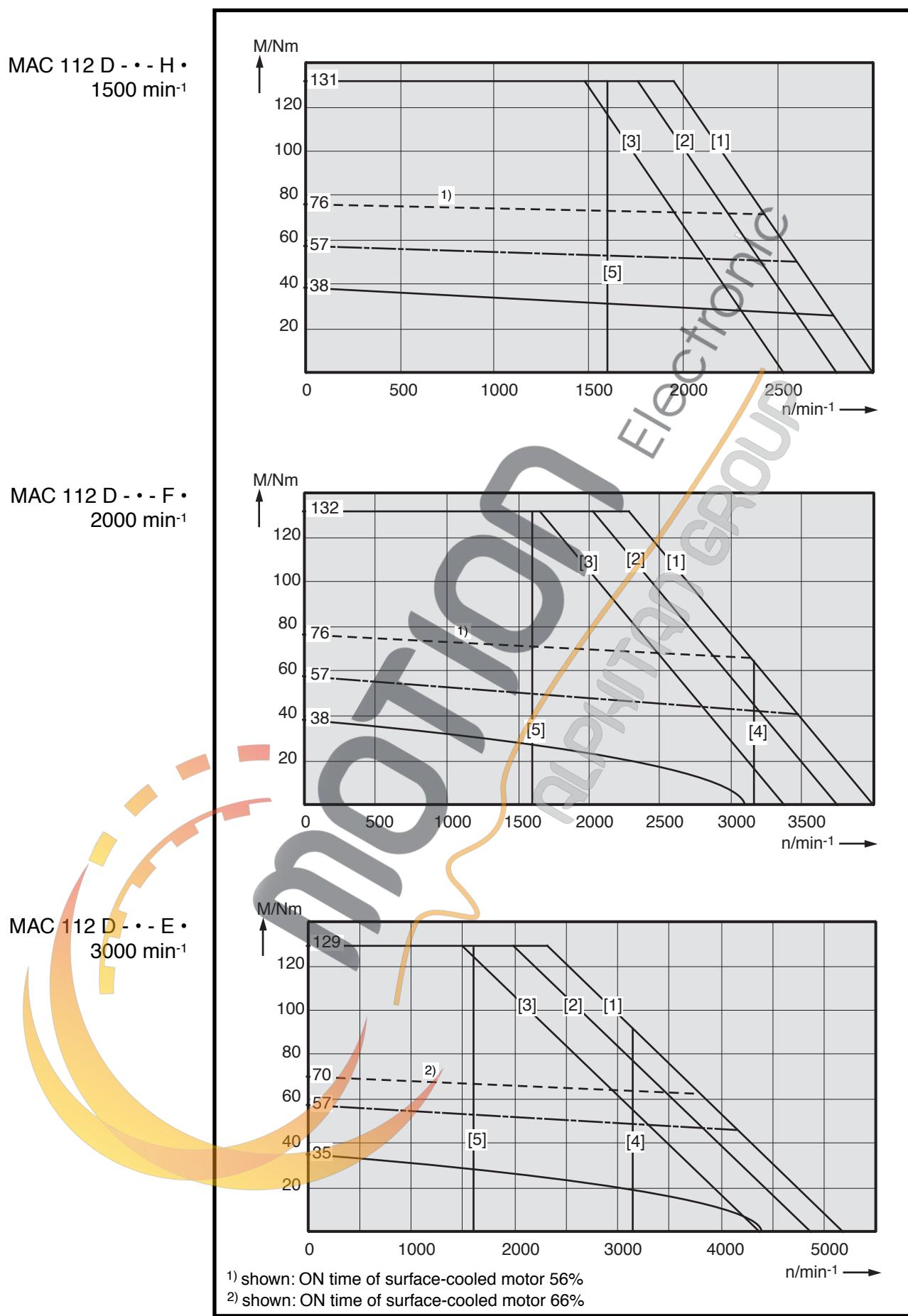


Fig 7.9: Torque-speed characteristics MAC 112

7.3. Shaft load capacity

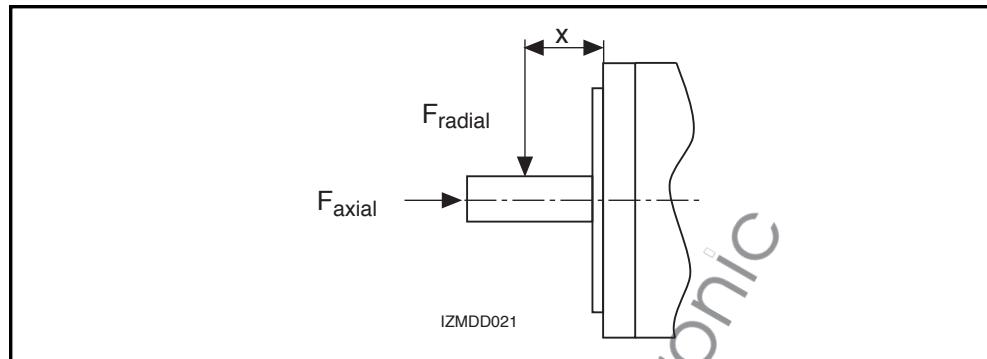


Fig 7.10: Shaft load

Permissible radial force
 F_{radial}

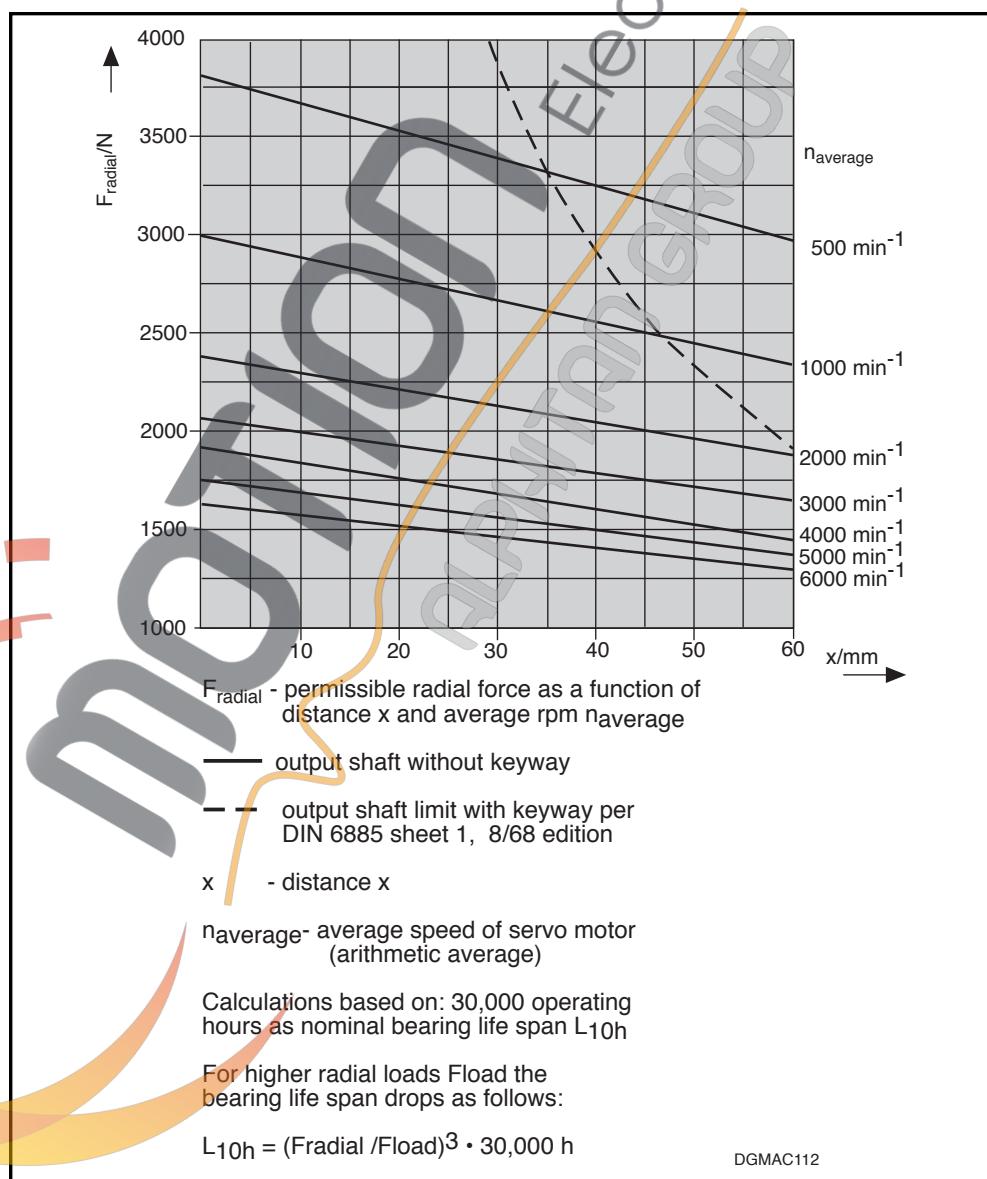


Fig 7.11: Permissible radial force

Permissible axial force
 F_{axial}

$$F_{\text{axial}} = 0.35 \cdot F_{\text{radial}}$$

F_{axial} - Permissible axial force

F_{radial} - Permissible radial force

7.4. Dimensional data - natural convection

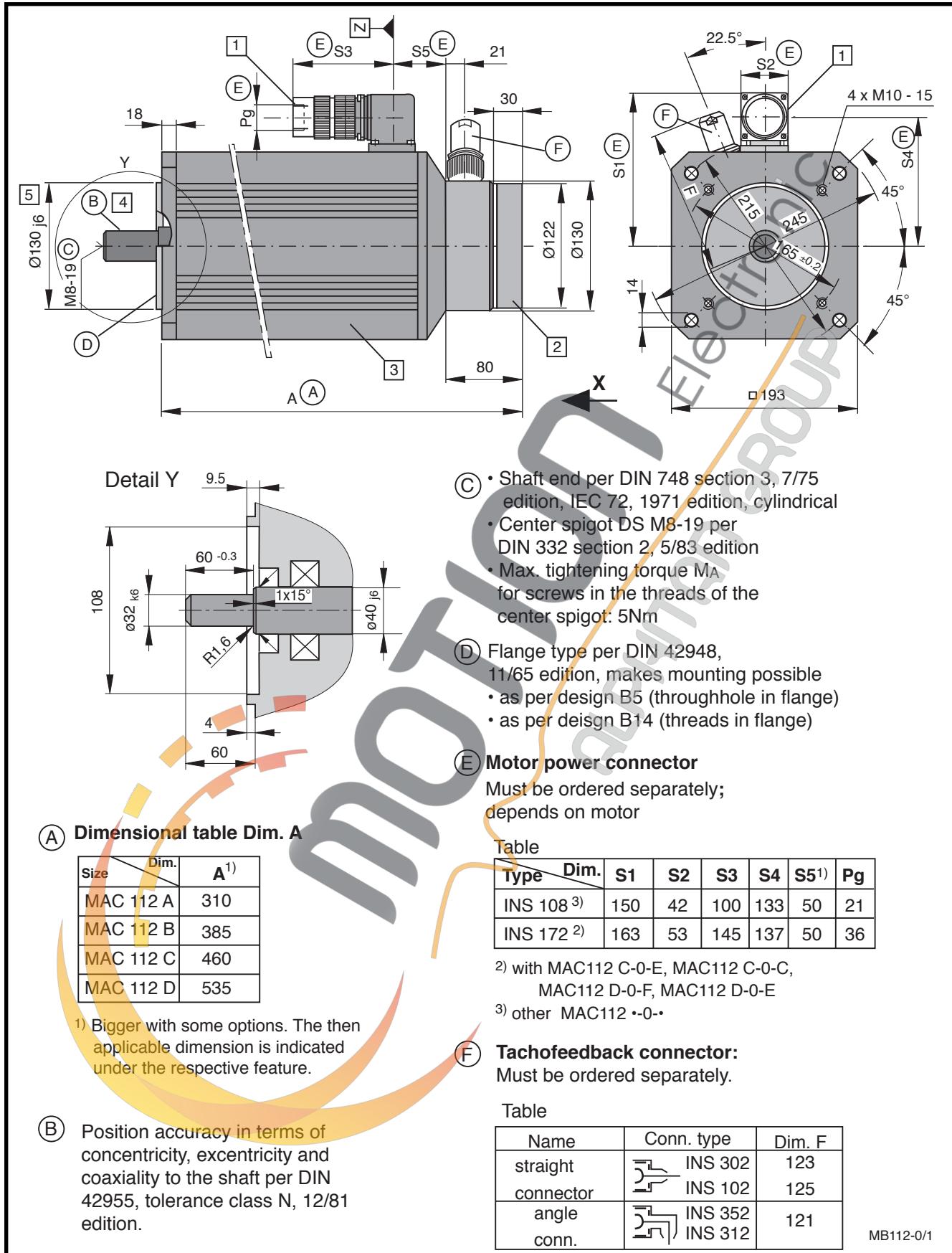


Fig 7.12: Dimensional data - MAC 112 (natural convection)

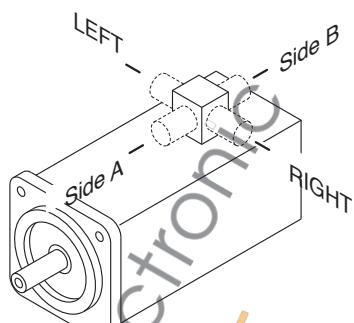
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

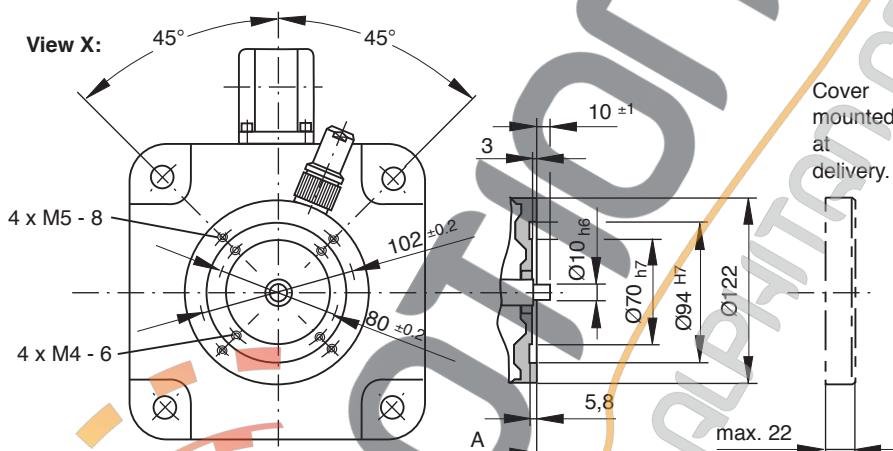
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.

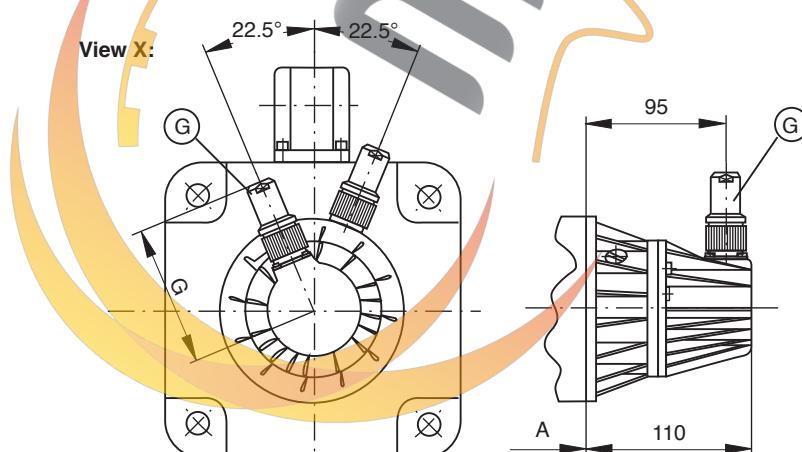


2 Motor version

- Tachofeedback and second shaft end



- Tachofeedback and mounted incremental encoder



G Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301 INS 101	88 90
angle conn.	INS 351 INS 311	86

- Tachofeedback and mounted absolute encoder (see following page)

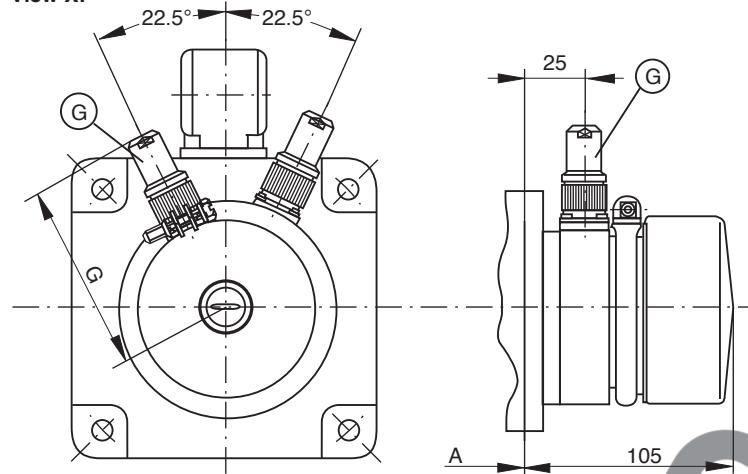
MB112-0/2

Fig 7.13: Dimensional data - MAC 112 - available options - (natural convection)

Available options

- Tachofeedback and mounted absolute encoder

View X:



Absolute encoder conn.
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326 INS 92	104 106
angle conn.	INS 322	102

3 Blocking brake

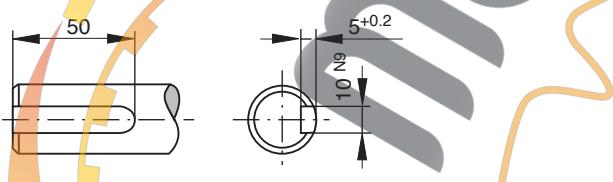
- without blocking brake
Dim. A and S5 retained
- Standard blocking brake: 14 Nm
Dim. A and S5 retained
- heavy-duty blocking brake: 40 Nm
(not available with MAC 112 A ...)
- extra heavy-duty blocking brake: 60 Nm
(not available with MAC 112 A ...)

Table for blocking brake
with 40 and 60 Nm

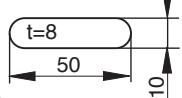
Size	Dim.	A	S5
MAC 112 B		435	98
MAC 112 C		510	98
MAC 112 D		585	98

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
(Note! balanced with entire key.)



Matching key: DIN 6885-A 10 x 8 x 50
Must be ordered separately.



5 Special centering diameter

- $\varnothing 180$ j6

MB112-0/3

Fig 7.14: Dimensional data - MAC 112 - available options - (natural convection)

7.5. Dimensional data - radial cooling

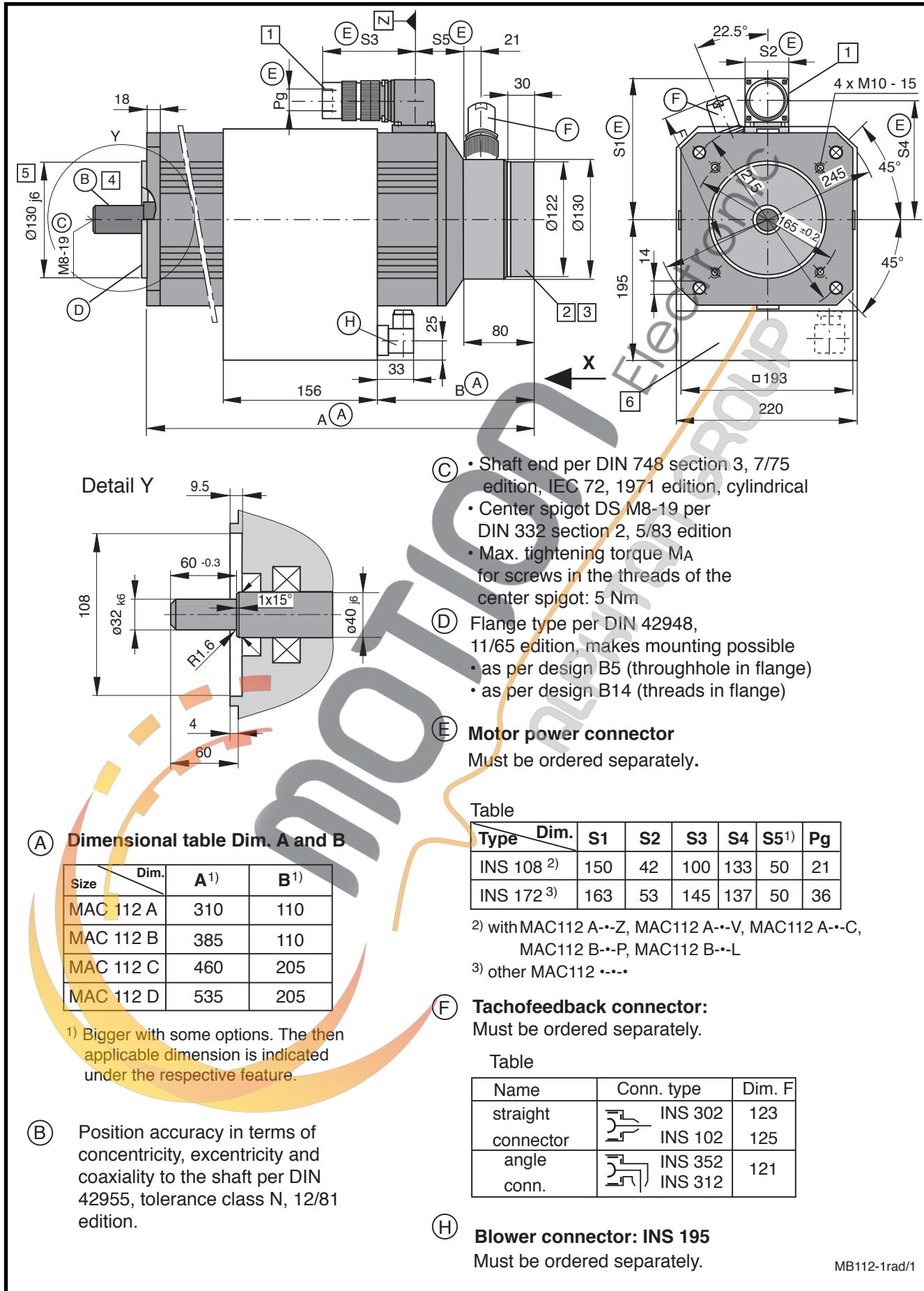


Fig 7.15: Dimensional data - MAC 112 (radial cooling)

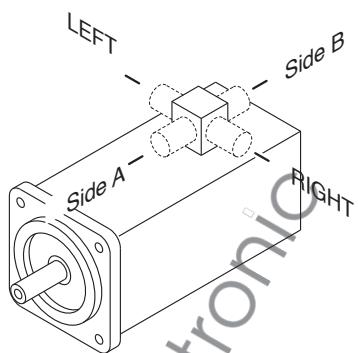
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

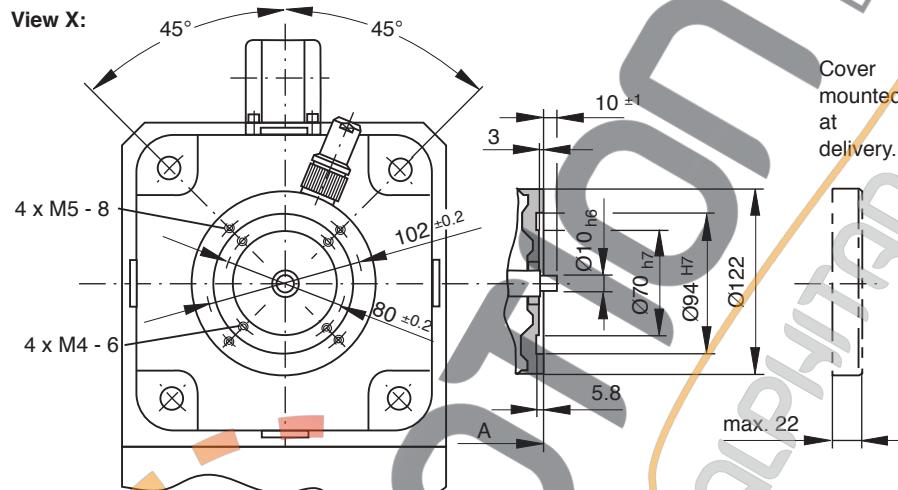
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.

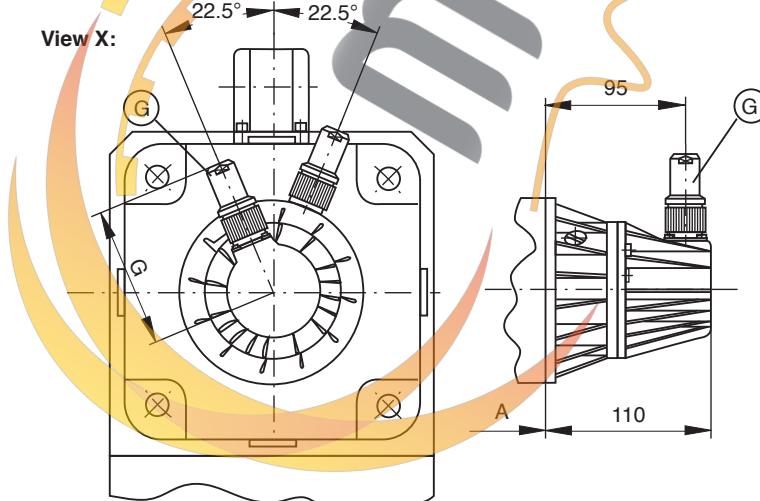


2 Motor version

- Tachofeedback and second shaft end



- Tachofeedback and mounted incremental encoder



- Tachofeedback and mounted absolute encoder
(see following page)

G Incremental encoder connector

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301 INS 101	88 90
angle conn.	INS 351 INS 311	86

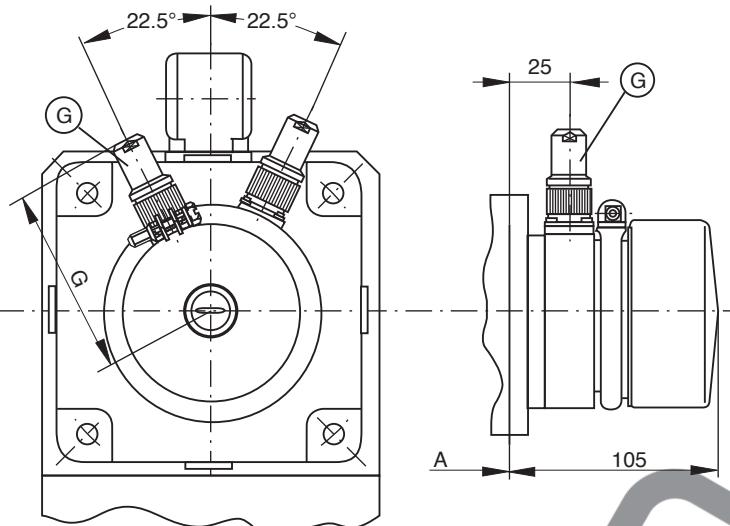
MB112-1rad/2

Fig 7.16: Dimensional data - MAC 112 - available options - (radial cooling)

Available options

- Tachofeedback and mounted absolute encoder

View X:



(G) **Absolute encoder conn.**
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326 INS 92	104 106
angle conn.	INS 322	102

3 Blocking brake

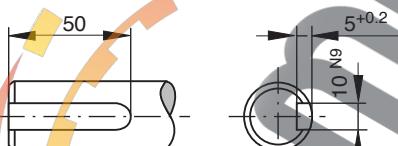
- without blocking brake
Dim. A, B and S5 retained
- Standard blocking brake: 14 Nm
Dim. A, B and S5 retained
- heavy-duty blocking brake: 40 Nm
(not available with MAC 112 A ...)
- extra heavy-duty blocking brake: 60 Nm
(not available with MAC 112 A ...)

Table for blocking brake
with 40 and 60 Nm

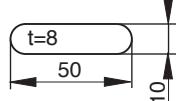
Size	Dim.	A	S5	B
MAC 112 B		435	98	160
MAC 112 C		510	98	255
MAC 112 D		585	98	255

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
(Note! balanced with entire key.)



Matching key: DIN 6885-A 10 x 8 x 50
Must be ordered separately.

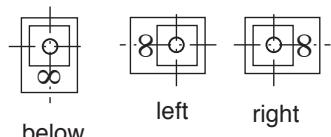


5 Special centering diameter

- $\varnothing 180 \text{ j6}$

6 Blower arrangement

Looking towards motor shaft.



MB112-1rad/3

Fig 7.17: Dimensional data - MAC 112 - available options - (radial cooling)

7.6. Dimensional data - axial cooling

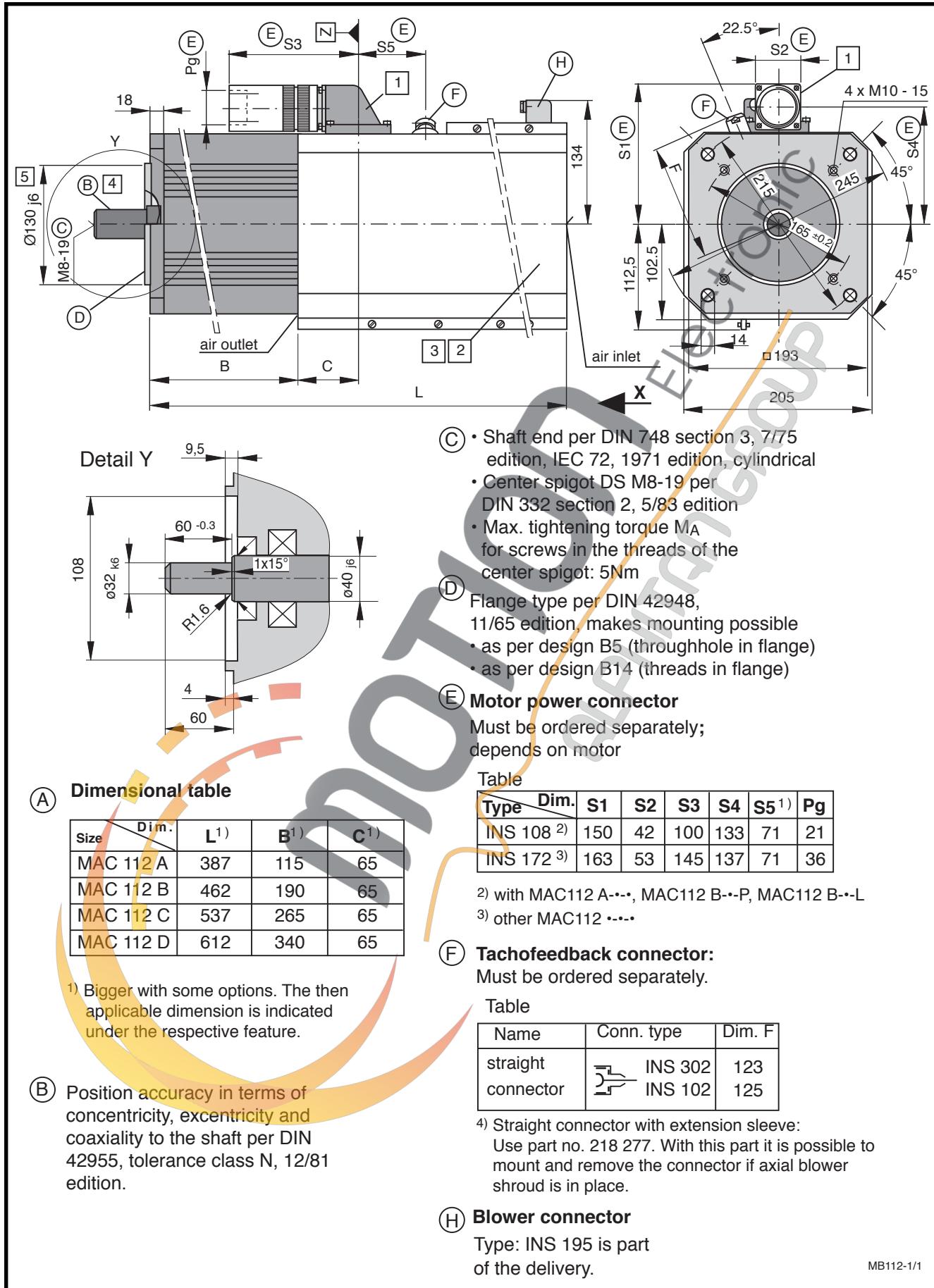


Fig 7.18: Dimensional data - MAC 112 (axial cooling)

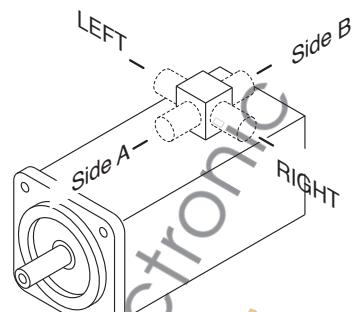
Available options

1 Power connection

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.



2 Motor version

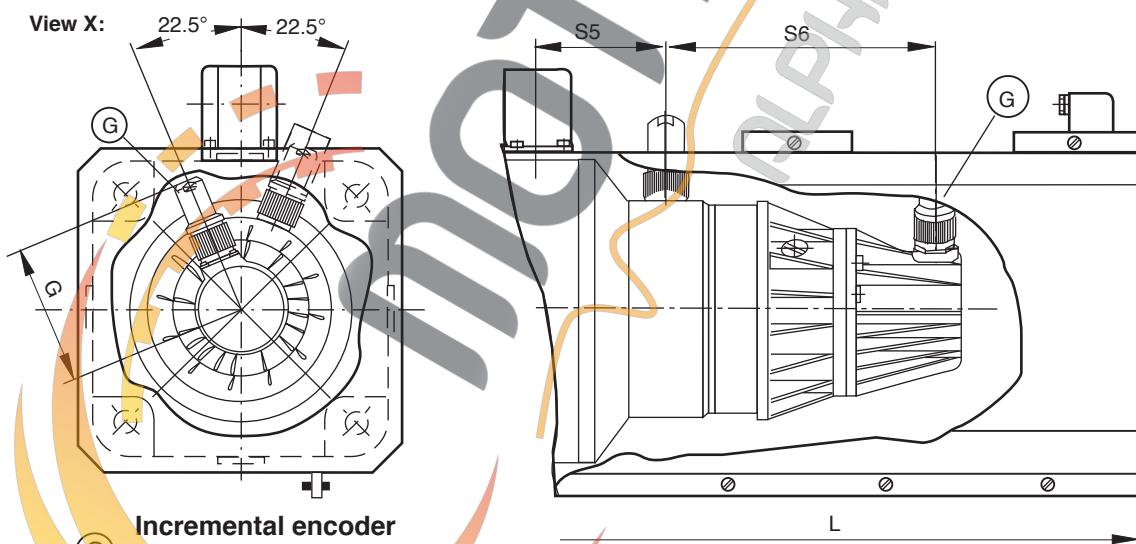
- Tachofeedback and incremental encoder

Table

Size	Dim.	L	B	C	S5	S6
MAC 112 A		497	115	65	71	154
MAC 112 B		572	190	65	71	154
MAC 112 C		647	265	65	71	154
MAC 112 D		722	340	65	71	154

Table for motors with blocking brakes of 40 Nm and 60 Nm

Size	Dim.	L	B	C	S5	S6
MAC 112 B		622	192	17	119	154
MAC 112 C		697	267	17	119	154
MAC 112 D		772	342	17	119	154



Must be ordered separately.

Name	Conn. type	Dim. G
straight conn. 1)	INS 301	123
	INS 101	125

1) Straight connector with extending sleeve:
part no.: 218 277

MB112-1/2

- Tachofeedback and mounted absolute encoder
(see following page)

Fig 7.19: Dimensional data - MAC 112 - available options - (axial cooling)

Available options

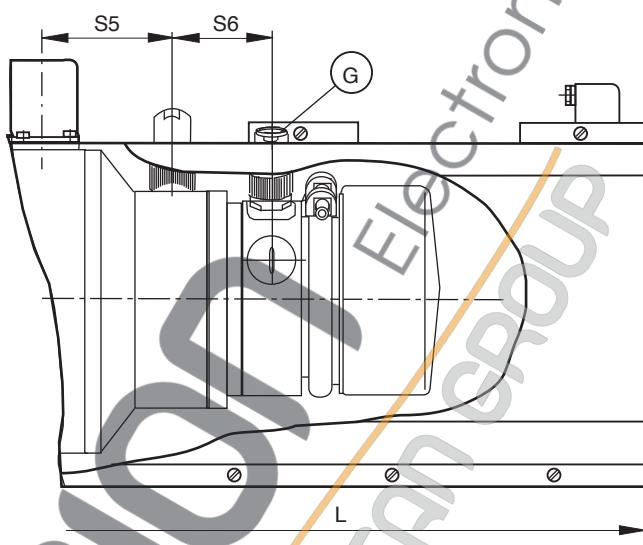
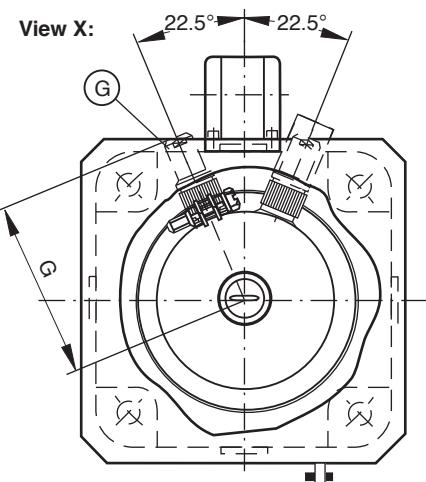
- Tachofeedback and mounted absolute encoder

Table

Size	Dim.	L	B	C	S5	S6
MAC 112 A		497	115	65	71	84
MAC 112 B		572	190	65	71	84
MAC 112 C		647	265	65	71	84
MAC 112 D		722	340	65	71	84

Table with blocking brake with 40 and 60 Nm holding torque

Size	Dim.	L	B	C	S5	S6
MAC 112 B		622	192	65	119	84
MAC 112 C		697	267	65	119	84
MAC 112 D		772	342	65	119	84



(G) Absolute encoder conn.

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326 INS 92	104 106

3 Blocking brake

- without blocking brake
Dim. L and B retained
- Standard blocking brake: 14 Nm
Dim. L and B retained
- heavy-duty blocking brake: 40 Nm
(not available with MAC 112A ...)
- extra heavy-duty blocking brake: 60 Nm
(not available with MAC 112A ...)

Table for blocking brake with 40 and 60 Nm

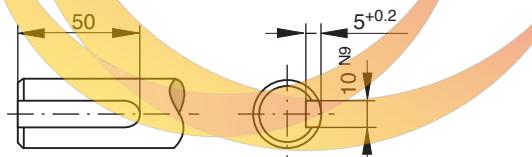
Size	Vers. 2		Vers. 4	
	L	B	L	B
MAC 112 B	512	240	622	240
MAC 112 C	587	315	697	315
MAC 112 D	662	390	772	390

Vers. 2 = Motor with tachofeedback

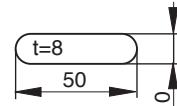
Vers. 4 = Motor with tachofeedback and mounted encoder

4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition
(Note! balanced with entire key.)



Matching key: DIN 6885-A 10 x 8 x 50
Must be ordered separately.



5 Special centering diameter

- $\varnothing 180$ j6

MB112-1/3

Fig 7.20: Dimensional data - MAC 112 - available options - (axial cooling)

7.7. Available Options

Type code fields				Example: MAC 112 A-0-LD-4 - C/130-A-0/WI 520LV/S000							
1. Motor for analogue drives	MAC										
2. Motor size	112										
3. Motor length	A, B, C, D										
4. Type of cooling:	natural convection										
	axial		surface cooling								
				blower right	blower below	blower left					
	AC 230 V	AC 115 V		AC 230 V	AC 115 V	AC 230 V	AC 115 V	AC 230 V	AC 115 V		
0	1) 2)	6	A	7	B	8	C				
5. Type of windings	Standard applications				with increased smooth run quality						
	Nominal rpm				motor length		motor length				
	A	B	C	D	A	B	C	D			
1500 min ⁻¹	ZD	PD	KD	HD	ZG	PG	KG	HG			
2000 min ⁻¹	VD	LD	HD	FD	VG	LG	HG	FG			
3000 min ⁻¹	LD	GD	ED	ED	LG	GG	EG	EG			
5000 min ⁻¹	--	--	CD 6)	--	--	--	CG 6)	--			
6. Motor feedback	Motor type with tachofeedback with tachofeedback and second shaft end with tachofeedback and mounted incremental or absolute encoder										
	Tacho voltage set to nominal motor speed (nominal rpm > 3000 min ⁻¹ : 1,5 V/1000 min ⁻¹) (Nenndrehzahl <= 3000 min ⁻¹ : 3 V/1000 min ⁻¹) 1,5 V/1000 min ⁻¹ 6 V/1000 min ⁻¹ 3)										
	Tacho type Standard increased smooth run quality										
	7. Centering diameter for design B05 and B14 for design B05 and B14										
	130 180 2)										
	8. Power connection connector to side A connector to side B connector to right (looking onto output shaft) connector to left (looking towards output shaft)										
	A B R L										
	9. Blocking brake without blocking brake with standard blocking brake (45 Nm) with heavy-duty blocking brake (60 Nm) extra heavy-duty blocking brake (60 Nm)										
	0 1 2 2) 5) 3 2) 5)										
	10. Type 4) Incremental encoder with standard mounting Incremental encoder with shock-damped mounting Absolute encoder										
	WI DI AM										
	11. Encoder code 4) For available types, see section 2.4 "Motor feedback"										
	12. Special types Fixed and documented by INDRAMAT with special number (see Drawing no.: 106-0105-4301-XX) Does not apply to standard motors.										
1)	For type 3 motors (with 2nd shaft end and tachofeedback). Not available with axial surface cooling.										
2)	Type code fields 10 and 11 do not apply to motor types 2 and 3.										
3)	only with tacho type "F"										
	4) type code fields 10 and 11 do not apply to motor types 2 and 3 5) not available with motor length A 6) not available with surface cooling										

Fig 7.21: Type codes - MAC 112

7.8. Special Options

Specification of Option	S003	S005	S011	S013	S018	S019	S029
Special centering diameter 180	X	X			X	X	
heavy-duty blocking brake			X	X	X	X	
with keyway per DIN 6885, sheet 1	X	X	X			X	

Fig 7.22: Special options with a MAC 112

